Randomness, Risk, and Electricity Prices

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- Define a welfare-maximizing outcome for society (optimization);
- Design a price mechanism that incentivizes this under assumptions about participant behaviour: perfect competition, complete markets, increasing marginal cost (complementarity);
- Test and improve the mechanism ex-ante in small-scale models as assumptions are relaxed to reflect reality (game theory);

- Implement the mechanism in practice and observe historical market outcomes (statistics);
- Benchmark historical outcomes against a theoretical competitive counterfactual.
 - Need large-scale models to replicate real system constraints
 - Better when equilibrium determined by optimization
 - When is this appropriate in presence of uncertainty?

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- 2 Design a pricing mechanism for two-stage stochastic model
 - deterministic example
 - two-stage stochastic example
 - generalization of example
- 3 Benchmark a multistage hydro system

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- At stage 2:
 - ▶ solar supplies \(\xi\$ at zero cost; \)
 - generator supplies y at cost y²;
 - \triangleright consumer consumes $z = x + y + \xi$;
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Maximize total system welfare

P:
$$\max_{x,y,z \ge 0} 16z - z^2 - \frac{1}{2}x^2 - y^2$$

s.t.
$$x + y + \xi \ge z$$

• The solution (x, y, z) to P maximizes the Lagrangian

$$16z - z^2 - \frac{1}{2}x^2 - y^2 + \pi(x + y + \xi - z)$$

where x, y, z and π satisfy

$$0 \le x + y + \xi - z \perp \pi \ge 0.$$

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Decomposition gives market equilbrium

• Each agent $a \in \{1, 2, 3, 4\}$ maximizes profit at prices π ,

P(1):
$$\max_{x \ge 0} \pi x - \frac{1}{2}x^2$$

P(2): $\max_{y \ge 0} \pi y - y^2$
P(3): $\max_{z \ge 0} 16z - z^2 - \pi z$
P(4): $\pi \xi$

where x, y, z and π satisfy equilibrium constraints

$$0 \leq x + y + \xi - z \perp \pi \geq 0.$$

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- Assume that agents treat π as a fixed parameter when they optimize, so this is not a model for imperfect competition.

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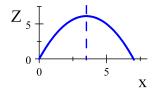
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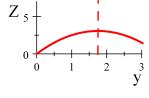
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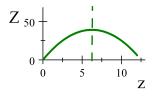
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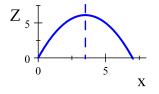
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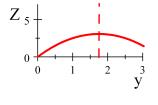


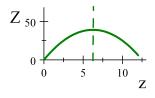




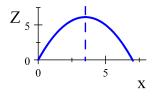
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- The generator collects $\pi = \$3.5$ per unit for 1.75 units.
- The solar generator collects $\pi = \$3.5$ per unit for 1 unit.
- The consumer pays $\pi = \$3.5$ per unit for 6.25 units.
- Total system welfare is 51.75.

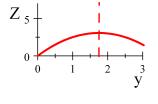


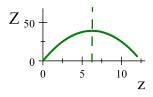




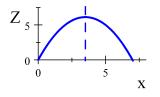
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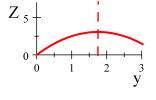


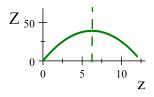




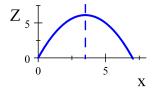
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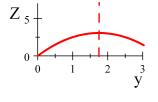


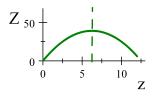




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Welfare theorems of partial equilibrium

Subject to conditions of convexity, completeness, and perfect competition we get:

- First welfare theorem: Suppose for some π , and each $a \in \mathcal{A}$, that x_a solves the agent problem P(a). If π and x satisfy the market clearing condition then x solves the system planning problem P.
- Second welfare theorem: If x solves the system planning problem P then there is some π so that each component x_a solves the agent problem P(a), and π and x satisfy the market clearing condition.

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Example: random sunshine

- At stage 1: battery stores energy x at cost $\frac{1}{2}x^2$.
- At stage 2:
 - ▶ solar supplies random $\xi(\omega)$ at zero cost;
 - generator supplies $y(\omega)$ at cost $y(\omega)^2$;
 - ▶ consumer consumes $z(\omega) = x + y(\omega) + \xi(\omega)$;
 - ▶ consumer utility for z is $16z-z^2$.
- Maximize expected welfare $\mathbb{E}[Z(x,\omega)]$ where

$$Z(x,\omega) = 16z(\omega) - z(\omega)^2 - y(\omega)^2 - \frac{1}{2}x^2$$

System optimization is a two-stage stochastic program

Suppose $\xi(\omega_1)=1$ and $\xi(\omega_2)=3$ with equal probability.

Optimal solution is

- x=3.
- $y(\omega_1)=2$ $y(\omega_2)=1$;
- $z(\omega_1)=6$ $z(\omega_2)=7$;
- $\pi(\omega_1)=4$ $\pi(\omega_2)=2$;

Solution value = $\mathbb{E}[Z(\mathbf{x},\omega)] = 54.5$.

Risk-neutral market equilbrium

A set of prices $\pi(\omega)$ and x^* , $y^*(\omega)$, $z^*(\omega)$ satisfying:

$$\begin{aligned} \mathbf{x}^* &\in \arg\max_{\mathbf{x} \geq 0} \quad \mathbb{E}[\pi(\omega)\mathbf{x} - \frac{1}{2}\mathbf{x}^2] \\ \mathbf{y}^*(\omega) &\in \arg\max_{\mathbf{y}(\omega) \geq 0} \quad \mathbb{E}[\pi(\omega)\mathbf{y}(\omega) - \mathbf{y}(\omega)^2], \\ \mathbf{z}^*(\omega) &\in \arg\max_{\mathbf{z}(\omega) \geq 0} \quad \mathbb{E}[16\mathbf{z}(\omega) - \mathbf{z}(\omega)^2 - \pi(\omega)\mathbf{z}(\omega)], \\ 0 &\leq \quad \mathbf{x}^* + \mathbf{y}^*(\omega) + \xi(\omega) - \mathbf{z}^*(\omega) \perp \pi(\omega) \quad \geq 0, \quad \omega \in \Omega. \end{aligned}$$

Payments and revenue adequacy

[Pritchard, Zakeri, P., 2010]

$$\pi(\omega_1) = \$4, \quad \pi(\omega_2) = \$2.$$

- Battery paid $\mathbb{E}[\pi] = \$3$ per unit for 3 units.
- Solar paid $\pi = \$4$ per unit for 1, $\pi = \$2$ per unit for 3.
- Generator paid $\pi = \$4$ per unit for 2, $\pi = \$2$ per unit for 1.
- Consumer pays $\pi = \$4$ per unit for 6, $\pi = \$2$ per unit for 7.
- Half the time there is a shortfall of \$3 and half the time a surplus of \$3. The market is not revenue adequate in every outcome.
 The market clearing agent bears the risk.

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Alternative payment scheme

[Zakeri et al, 2018], [Cory-Wright et al, 2018]

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- Half the time the battery is producing at a loss. Risk is transferred from the auctioneer to battery.
- Battery bears the cost of nonanticipativity [c.f. de Maere d'Aertrycke, Shapiro, Smeers, 2013].

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Observations

- Two-stage stochastic program gives a market design assuming risk neutrality for all players.
- Maximizing expected social welfare will give shortfalls when participants and market clearing agent are risk averse.
- Motivates a price mechanism for risk-averse participants, which will deliver an optimal risk-adjusted social planning solution.

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Example: risk-averse agents

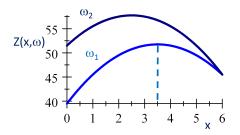
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 - consumer utility for z is $16z-z^2$.
- Maximize risk-adjusted welfare $\mathbb{F}[Z(x,\omega)]$ where \mathbb{F} is defined by a risk measure.

Example: \mathbb{F} is worst-case (\mathbb{W})

maximize worst-case social welfare:

$$\max_{\mathbf{x} \geq \mathbf{0}, \mathbf{y}(\omega) \geq 0} \min \{ Z(\mathbf{x}, \omega_1), Z(\mathbf{x}, \omega_2) \}$$

$$Z(\mathbf{x}, \omega) = 16(\mathbf{x} + \mathbf{y}(\omega) + \boldsymbol{\xi}(\omega)) - (\mathbf{x} + \mathbf{y}(\omega) + \boldsymbol{\xi}(\omega))^2 - \frac{1}{2}\mathbf{x}^2 - \mathbf{y}(\omega)^2$$



Solution x = 3.5, worst-case is ω_1 , risk adjusted value is 51.75.

Risk-averse equilibrium

A set of prices $\pi(\omega)$ and x^* , $y^*(\omega)$, $z^*(\omega)$ satisfying:

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Risked equilibria: \mathbb{F} is worst-case (\mathbb{W})

Α	ξ	π	<i>x</i> *	<i>y</i> *	z*	Z	Ζ	Z	Z
ω_1	1	4.5	2.5	2.25	5.75	8.13	5.06	33.06	4.5
ω_2	3	2.5	2.5	1.25	6.75	3.13	1.56	45.56	7.5

Unique competitive equilibrium A if $y^*(\omega)$ and $z^*(\omega)$ are constrained to be optimal for each ω (risk-adjusted system welfare=50.75).

В	ξ	π	<i>x</i> *	<i>y</i> *	Z^*	Z	Z	Z	Z
ω_1	1	3.31	3.09	2.25	6.34	5.46	2.39	40.24	3.31
ω_2	3	3.09	3.09	1.55	7.64	4.78	2.39	40.24	9.27

Best alternative equilibrium B: $y^*(\omega_1)$ is not optimal for ω_1 . $z^*(\omega_2)$ is not optimal for ω_2 (risk-adjusted system welfare=51.41).

Monotonicity

[Shapiro, 2017]

- \mathbb{F} is monotone if $Z_1 \leq Z_2$ implies $\mathbb{F}(Z_1) \leq \mathbb{F}(Z_2)$.
- \mathbb{F} is strictly monotone if \mathbb{F} is monotone, and $Z_1 \leq Z_2$ and $Z_1 \neq Z_2$ implies $\mathbb{F}(Z_1) < \mathbb{F}(Z_2)$.
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[Shapiro, 2017]

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- \mathbb{F} is strictly monotone if \mathbb{F} is monotone, and $Z_1 \leq Z_2$ and $Z_1 \neq Z_2$ implies $\mathbb{F}(Z_1) < \mathbb{F}(Z_2)$.
- ullet $\mathbb{F}=\mathbb{W}$ (worst case) is monotone but not strictly monotone.

- GOOD: Risked social plan gives unique x=3.5 for this example, and $y(\omega_1)=1.75$. BAD: $y(\omega_2)$ is not uniquely determined.
- BAD: Risk-averse competitive equilibrium is not unique.
- **3** GOOD: The social plan is unique if \mathbb{F} is strictly monotone, for example $\mathbb{F} = \lambda \mathbb{E} + (1 \lambda) \mathbb{W}$ where $\lambda > 0$.
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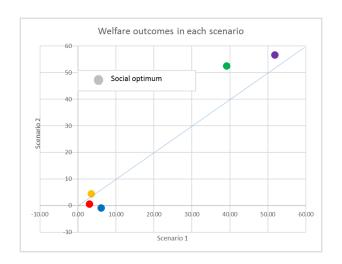


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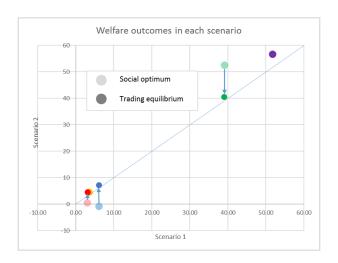


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Social plan welfare outcomes: worst-case measure



Trading makes social plan a risk-averse equilibrium



- Risk neutral social optimum (54.5) cannot be achieved by prices that give revenue adequacy and cost recovery in every scenario.
- Risk-averse social optimal solution (51.75) has higher risk-adjusted system welfare than the best risk-averse competitive equilibrium (51.4), so social optimal solution is not an equilibrium.
- Risk-averse social optimal solution turns into an equilibrium with risk-adjusted social welfare 51.75 if agents can trade risk.
- Conversely, if agents can trade risk as well as energy then the resulting risk-averse equilibrium will maximize risk-adjusted social welfare.
- With trading, all agents ignore scenario 2. Prices from scenario 1 system optimal solution (x = 3.5) give risk-averse equilibrium. Revenue adequacy and cost recovery is achieved in risk-adjusted expectation.

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Assume a finite sample space for simplicity.

- Worst-case in a minimization setting is an example of a coherent risk measure. Other examples are expectation and average value at risk (AVaR).
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Trading risk: Arrow-Debreu securities

- An Arrow-Debreu security for outcome $\omega \in \Omega$ in stage 2 is a contract that has a payout of 1 in outcome ω . We denote the price of such a contract in stage 1 by $\mu(\omega)$.
- Suppose that each agent buys $W_a(\omega)$ Arrow-Debreu securities at stage one, costing $\mu^\top W_a = \sum_{\omega \in \Omega} \mu(\omega) W_a(\omega)$, to receive return $W_a(\omega)$ in outcome ω in stage 2.
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Risk-averse equilibrium

A set of prices $\pi(\omega)$, and x^* , y^* , z^* , satisfying:

$$(x^*) \in \arg\max \mathbb{F}[\pi(\omega)x - \frac{1}{2}x^2]$$

$$(\qquad \qquad \mathbf{y^*}(\omega)) \in \operatorname{\mathsf{arg}} \operatorname{\mathsf{max}} \mathbb{F}[\pi(\omega)\mathbf{y}(\omega) - \mathbf{y}(\omega)^2 \qquad \qquad]$$

$$(z^*(\omega)) \in \arg\max \mathbb{F}[16z(\omega) - z(\omega)^2 - \pi(\omega)z(\omega)]$$

$$0 \le x^* + y^*(\omega) + \xi(\omega) - z^*(\omega) \perp \pi(\omega) \ge 0, \omega \in \Omega.$$

Risk-averse equilibrium with Arrow-Debreu securities

A set of prices $\pi(\omega)$, $\mu(\omega)$ and x^* , y^* , z^* , W^* satisfying:

$$\begin{split} &(\textit{W}_1^*(\omega), \textit{x}^*) \in \arg\max \mathbb{F}[\pi(\omega)\textit{x} - \frac{1}{2}\textit{x}^2 + \textit{W}_1(\omega)] - \mu^\top \textit{W}_1 \\ &(\textit{W}_2^*(\omega), \textit{y}^*(\omega)) \in \arg\max \mathbb{F}[\pi(\omega)\textit{y}(\omega) - \textit{y}(\omega)^2 + \textit{W}_2(\omega)] - \mu^\top \textit{W}_2, \\ &(\textit{W}_3^*(\omega), \textit{z}^*(\omega)) \in \arg\max \mathbb{F}[16\textit{z}(\omega) - \textit{z}(\omega)^2 - \pi(\omega)\textit{z}(\omega) + \textit{W}_3(\omega)] \\ &- \mu^\top \textit{W}_3, \end{split}$$

$$&(\textit{W}_4^*(\omega)) \in \arg\max \mathbb{F}[\pi(\omega)\xi(\omega) + \textit{W}_4(\omega)] - \mu^\top \textit{W}_4, \\ &0 \leq -\textit{W}_1^*(\omega) - \textit{W}_2^*(\omega) - \textit{W}_3^*(\omega) - \textit{W}_4^*(\omega) \perp \mu(\omega) \geq 0, \omega \in \Omega, \\ &0 \leq \textit{x}^* + \textit{y}^*(\omega) + \xi(\omega) - \textit{z}^*(\omega) \perp \pi(\omega) \geq 0, \omega \in \Omega. \end{split}$$

Welfare Theorems

[Ralph and Smeers, 2015], [Gerard et al, 2018]

Suppose agents have coherent risk measures with risk sets \mathcal{D}_a with $\bigcap_{a\in\mathcal{A}}\mathcal{D}_a\neq\emptyset$, and there is a complete market for A-D securities.

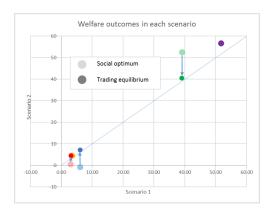
Theorem

If $\{\pi(\omega), \omega \in \Omega\}$, and $\{\mu(\omega), \omega \in \Omega\}$ give a risk-averse equilibrium $\{(W_1^*(\omega), x^*), (W_2^*(\omega), y^*(\omega)), (W_3^*(\omega), z^*(\omega)), W_4^*(\omega)\}$ then $\{x^*, y^*(\omega), z^*(\omega)\}$ solves the risk-averse social planning problem with risk measure having risk set $\mathcal{D}_s = \bigcap_{a \in \mathcal{A}} \mathcal{D}_a$.

Theorem

If $\{x^*,y^*(\omega),z^*(\omega)\}$ solves the risk-averse social planning problem SP with risk set $\mathcal{D}_s = \bigcap_{a \in \mathcal{A}} \mathcal{D}_a$ then there exists prices $\{\pi(\omega), \omega \in \Omega\}$, and $\{\mu(\omega), \omega \in \Omega\}$ and trades in A-D securities so that $\{(W_1^*(\omega),x^*),(W_2^*(\omega),y^*(\omega)),(W_3^*(\omega),z^*(\omega)),W_4^*(\omega)\}$ is a risk-averse equilibrium.

Example with worst case $\mathbb{F}=\mathbb{W}$



Equilibrium prices of A-D Securities are $\mu(\omega_1)=1$, $\mu(\omega_2)=0$. Agent a can acquire $W_a(\omega_2)$ at zero cost as long as $0 \leq -W_1^*(\omega_2) - W_2^*(\omega_2) - W_3^*(\omega_2) - W_4^*(\omega_2)$.

Summary

- Introduction
- Design a pricing mechanism for two-stage stochastic model
 - deterministic example
 - two-stage stochastic example
 - generalization of example
- 3 Benchmark a multistage hydro system

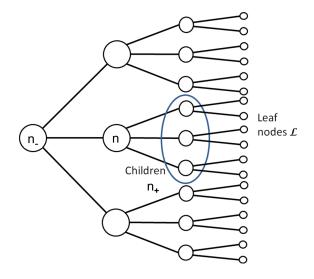
Hydroelectricity reservoir optimization



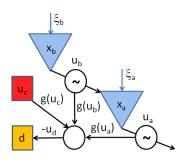
Ohau A power station in New Zealand's South Island

(Photo by By Ulrich Lange, Bochum, Germany - Own work)

A scenario tree represents uncertain inflow outcomes



Hydroelectric optimization and equilibrium with storage



Storage (i.e. batteries, hydroelectric reservoirs, pumped storage) adds dynamics. We have a storage state variable x_a for agent a affected by controls (e.g. reservoir releases, u, possibly from other agents) and random disturbances ξ (e.g. inflows).

$$x_a(n) \le x_a(n_-) + \sum_{b \in A} T_{ab} u_b(n) + \xi_a(n), \quad a \in \mathcal{A}, n \in \mathcal{N}.$$

In each node $n \in \mathcal{N}$, agents produce electricity to meet demand (that is also treated as an agent).

- Controls $u(m) \in \mathcal{N} \setminus \{0\}$ give benefits $Z(m), m \in \mathcal{N} \setminus \{0\}$.
- Assume known future risk-adjusted benefit $\theta(n)$ in node $n \in \mathcal{L}$.
- polyhedral risk sets $\mathcal{D}(n)$, $n \in \mathcal{N}$ with known extreme points $\{\mathbb{P}^k(m), m \in n_+, k \in \mathcal{K}(n)\}$.
- Risk adjustment is recursive:

$$\theta(n) = \min_{\mathbb{P} \in \mathcal{D}(n)} \sum_{m \in n_{+}} \mathbb{P}(m)(Z(m) + \theta(m))$$

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A multistage risk-averse optimization problem with storage (P., Ferris, Wets, 2016, Ferris and P., 2018)

$$\begin{aligned} \mathsf{SO}(\mathcal{D}) \colon & \max_{u, x, \theta} \theta(0) - \sum_{a \in \mathcal{A}} C_a(u_a(0)) \\ & \mathsf{s.t.} \ \theta(n) = \min_{\mathbb{P} \in \mathcal{D}(n)} \sum_{m \in n_+} \mathbb{P}(m) (-\sum_{a \in \mathcal{A}} C_a(u_a(m)) + \theta(m)), \\ & x_a(n) \le x_a(n_-) + \sum_{b \in \mathcal{A}} T_{ab} u_b(n) + \xi_a(n), \quad [\mathsf{water}] \\ & \sum_{a \in \mathcal{A}} g_a(u_a(n)) \ge 0 \quad [\mathsf{energy}] \\ & \theta(n) = \sum_{a \in \mathcal{A}} V_a(x_a(n)), \quad n \in \mathcal{L}, \\ & u_a(n) \in \mathcal{U}_a, \quad x_a(n) \in \mathcal{X}_a, \quad n \in \mathcal{N}, \quad a \in \mathcal{A}. \end{aligned}$$

New definitions for multistage

Definition

For $n \in \mathcal{N} \setminus \mathcal{L}$ the social planning risk set is

$$\mathcal{D}_s(n) = \bigcap_{a \in \mathcal{A}} \mathcal{D}_a(n).$$

Definition

Given any node $n \in \mathcal{N} \setminus \mathcal{L}$, an Arrow-Debreu security for node $m \in n_+$ is a contract that charges a price $\mu(m)$ in node n to receive a payment of 1 in node $m \in n_+$.

Some assumptions

• Assumption 1: All risk sets $\mathcal{D}_a(n)$ lie strictly inside the positive orthant, implying strictly monotone \mathbb{F}_a .

• Assumption 2: (Complete risk markets) At every node $n \in \mathcal{N} \setminus \mathcal{L}$, there is an Arrow-Debreu security for each child node $m \in n_+$.

• Assumption 3: For $n \in \mathcal{N} \setminus \mathcal{L}$, $\mathcal{D}_s(n) \neq \emptyset$, i.e.

$$\bigcap_{a\in\mathcal{A}}\mathcal{D}_a(n)\neq\emptyset.$$

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- Assumption 2: (Complete risk markets) At every node $n \in \mathcal{N} \setminus \mathcal{L}$, there is an Arrow-Debreu security for each child node $m \in n_+$.
- Assumption 3: For $n \in \mathcal{N} \setminus \mathcal{L}$, $\mathcal{D}_s(n) \neq \emptyset$, i.e.

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Multistage risk-averse agent optimization

$$AO_a(\pi, \alpha, \mu, \mathcal{D}_a)$$
: $\max_{u_a, x_a, W_a, \theta_a} Z_a^0(u, x, W) + \theta_a(0)$

s.t.

$$\theta_a(n) = \min_{\mathbb{P} \in \mathcal{D}(n)} \sum_{m \in n_+} \mathbb{P}(m) (Z_a^m(u_a, x_a, W_a) + W_a(m) + \theta_a(m)),$$

$$\theta_a(n) = V_a(x_a(n)), \quad n \in \mathcal{L},$$

$$u_a(n) = V_a(x_a(n)), \quad n \in \mathcal{L},$$

 $u_a(n) \in \mathcal{U}_a, \ x_a(n) \in \mathcal{X}_a, \quad n \in \mathcal{N},$

$$\begin{split} Z_a^n(u,x,W) = & \quad \pi(n)g_a(u_a(n)) - C_a(u_a(n)) \text{ [energy profit]} \\ & \quad + \alpha_a(n)\left(x_a(n_-) - x_a(n) + \xi_a(n)\right) \text{ [stored water]} \\ & \quad + \sum_{b \in \mathcal{A}} \alpha_b(n)T_{ba}u_a(n) \text{ [transferred water]} \\ & \quad - \sum_{m \in n_+} \mu(m)W_a(m). \quad \text{[cost of A-D purchases]} \end{split}$$

Multistage risk-trading equilibrium

A multistage risk-trading equilibrium RTE($\mathcal{D}_{\mathcal{A}}$) is a stochastic process of prices $\{\pi(n)\}$, $\{\alpha_a(n)\}$, $\{\mu(n)\}$, and a corresponding collection of actions, $\{u_a^*(n)\}$, $\{x_a^*(n)\}$, $\{W_a^*(n)\}$, $\{\theta_a^*(n)\}$ with the property that $(u_a^*, x_a^*, W_a^*, \theta_a^*)$ solves the problem $AO_a(\pi, \alpha, \mu, \mathcal{D}_a)$, and at every node $n \in \mathcal{N}$

$$\begin{array}{lll} 0 \leq \pi(n) & \perp & \sum_{a \in \mathcal{A}} g_a(u_a^*(n)) \geq 0, & \text{[energy market]} \\ \\ 0 \leq \alpha_a(n) & \perp & -x_a^*(n) + x_a^*(n_-) + \sum_{b \in \mathcal{A}} T_{ab} u_b^*(n) + \xi_a(n) \geq 0, \\ \\ & \text{[water market]} \\ \\ 0 \leq \mu(n) & \perp & -\sum_{a \in \mathcal{A}} W_a^*(n) \geq 0, & \text{[risk market]}. \end{array}$$

First welfare theorem

[Ferris and P., 2018]

Suppose Assumptions 1 and 2 hold, and consider a set of agents $a \in \mathcal{A}$, each endowed with a polyhedral node-dependent risk set $\mathcal{D}_a(n)$, $n \in \mathcal{N} \setminus \mathcal{L}$ satisfying Assumption 3.

Theorem

If $\{\pi(n)\}$, $\{\alpha_a(n)\}$, and $\{\mu(n)\}$ form a multistage risk-trading equilibrium with $\{u_a^*(n)\}$, $\{x_a^*(n)\}$, $\{W_a^*(n)\}$, $\{\theta_a^*(n)\}$, then (u^*, x^*, θ_s^*) is a solution to $SO(\mathcal{D}_s)$ where $\mathcal{D}_s(n) = \bigcap_{a \in \mathcal{A}} \mathcal{D}_a(n)$ and $\theta_s^*(n) = \sum_{a \in \mathcal{A}} \theta_a^*(n)$.

Second welfare theorem

[P., Ferris, Wets, 2016]

Suppose Assumptions 1 and 2 hold, and consider a set of agents $a \in \mathcal{A}$, each endowed with a polyhedral node-dependent risk set $\mathcal{D}_a(n)$ satisfying Assumption 3.

Theorem

Let (u^*, x^*, θ_s^*) be a solution to $SO(\mathcal{D}_s)$ with risk sets $\mathcal{D}_s(n) = \bigcap_{a \in \mathcal{A}} \mathcal{D}_a(n)$, giving rise to Lagrange multipliers $\alpha_a(n)$ (for storage) and $\pi(n)$ (for energy). Then there exists $\mu(n)$ so that the prices $\{\pi(n)\}$, $\{\alpha_a(n)\}$, $\{\mu(n)\}$ and actions $\{u_a^*(n)\}$, $\{x_a^*(n)\}$, $\{W_a^*(n)\}$, $\{\theta_a^*(n)\}$ form a multistage risk-trading equilibrium.

- NZ uses a standard nodal pricing market design with 250 nodes.
- Wholesale market is dispatched every 30 minutes using optimization software called SPD.
 - energy (and spinning reserve) offers submitted by generators;
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- We use a counterfactual value of water based on a system optimization using risk-averse SDDP [Shapiro et al, 2013, P., de Matos, Finardi, 2013].
- We use 35 historical inflow sequences to train SDDP policy and a nested coherent risk measure based on a one-step conditional risk measure equal to $0.5\mathbb{E} + 0.5\mathbb{W}$.
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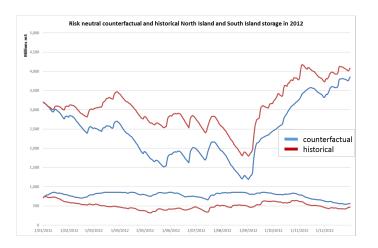
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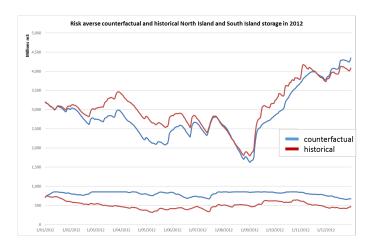
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South Island reservoir storage 2012



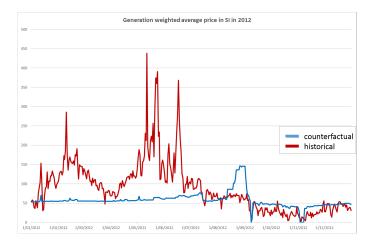
Storage levels from risk-neutral benchmark simulation compared with historical (market) levels in 2012.

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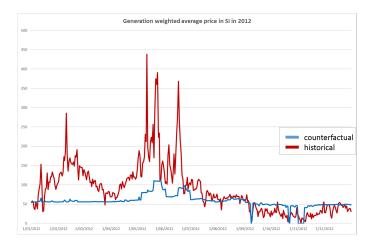
Storage levels from risk-averse benchmark simulation compared with historical (market) levels in 2012.

South Island wholesale electricity prices 2012



Generation-weighted average price from risk-neutral benchmark simulation compared with historical (market) prices in 2012.

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